Feasibility in stochastic programming An argument against constraints

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Feasibility comes naturally in two forms:

- Book-keeping constraints, typically inventory and conservation-of-flow
- Resource constraints

The first set is very useful, the second set a source of trouble.

The knapsack problem



where:

 c_i is the value of item i,

w_i its weight, and

b is the capacity of the knapsack.

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Inherently multi-stage (operational) models are models where all stages in principle are of the same type. Examples are production-inventory models, financial portfolio models and project scheduling.

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 - We learn the weight of the full set of items just after we decide what items to put in.
- The first two will normally lead to inherently multi-stage models, the third to inherently two-stage models.

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- We may pick a set of items of maximal value so that the probability that the items will not fit is below a certain level.

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But what if we want to pick the items one by one and then continue as long as there is still room?

• This will most likely lead to a very hard multi-stage model.

They must all fit ...

This is a worst-case setting. Is this really what you want? What can happen with such an approach?

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- But what if an item does not fit? Is there nothing we can do?
- Send it the next day? With another mode? By mail? Put the last box in the passenger seat?

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- A model which requires all items to fit, but where it is still very likely that they don't.

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Instead, use penalties to represent resource constraints, if necessary with very high penalties, but not ∞ .

Two-stage model

$$\max \sum_{i=1}^{n} c_{i}x_{i} - d\sum_{s \in S} p^{s}z^{s}$$
such that
$$\begin{cases} \sum_{i=1}^{n} w_{i}^{s}x_{i} - z^{s} \leq b & \forall s \in S \\ z^{s} \geq 0 & \forall s \in S \\ x_{i} \in \{0, 1\} & 1 = 1, \dots, n \end{cases}$$
(2)

where *d* is the unit penalty for overweight. We call this a *penalty formulation* since it can be replaced by

$$\max_{x_i \in \{0,1\}} \sum_{i=1}^n c_i x_i - d \sum_{s \in S} p^s \left[\sum_{i=1}^n w_i^s x_i - b \right]_+$$
(3)

where $[x]_+$ is equal to x if $x \ge 0$, zero otherwise.

Chance constrained formulation

$$\max_{x_i \in \{0,1\}} \sum_{i=1}^{n} c_i x_i$$
such that
$$\begin{cases} \sum_{s \in W(x)} p^s \ge \alpha \\ W(x) = \{s : \sum_{i=1}^{n} w_i^s x_i \le b\} \end{cases}$$
(4)

where α is the required probability of feasibility.

Note that this model (as the worst-case model) is sensitive to parameters. It depends seriously on the worst-case weights.

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- Use penalties instead, very high ones if need be.
- Remember the difference between "must be done" and "must be done within the model".
- Be particularly careful when "worst-case" is not well understood.
- Remember that a hard constraint means: I am willing to pay *any finite amount* to make this true.

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